# EXTREMAL FIRST DIRICHLET EIGENVALUE OF DOUBLY CONNECTED PLANE DOMAINS AND DIHEDRAL SYMMETRY

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ABSTRACT. We deal with the following eigenvalue optimization problem: Given a bounded domain  $D \subset \mathbb{R}^2$ , how to place an obstacle B of fixed shape within D so as to maximize or minimize the fundamental eigenvalue  $\lambda_1$  of the Dirichlet Laplacian on  $D \setminus B$ . This means that we want to extremize the function  $\rho \mapsto \lambda_1(D \setminus \rho(B))$ , where  $\rho$  runs over the set of rigid motions such that  $\rho(B) \subset D$ . We answer this problem in the case where both D and B are invariant under the action of a dihedral group  $\mathbb{D}_n$ ,  $n \geq 2$ , and where the distance from the origin to the boundary is monotonous as a function of the argument between two axes of symmetry. The extremal configurations correspond to the cases where the axes of symmetry of B coincide with those of D.

## 1. Introduction and Statement of the main Result

The relations between the shape of a domain and the eigenvalues of its Dirichlet or Neumann Laplacian, have been intensively investigated since the 1920's when Faber [5] and Krahn [12] have proved independently the famous eigenvalue isoperimetric inequality first conjectured by Rayleigh (1877): the first Dirichlet eigenvalue  $\lambda_1(\Omega)$  of any bounded domain  $\Omega \subset \mathbb{R}^n$  satisfies

$$\lambda_1(\Omega) \geq \lambda_1(\Omega^*),$$

where  $\Omega^*$  is a ball having the same volume as  $\Omega$ . We refer to the review papers of Ashbaugh [1, 2] and Henrot [9] for a survey of recent results on optimization problems involving eigenvalues.

The present work deals with the following eigenvalue optimization problem: Given a bounded domain D, we want to place an obstacle (or a hole) B, of fixed shape, inside D so as to maximize or minimize the fundamental eigenvalue  $\lambda_1$  of the Laplacian or Schrödinger operator on  $D \setminus B$  with Zero Dirichlet conditions on the boundary.

In other words, the problem is to optimize the principal eigenvalue function  $\rho \mapsto \lambda_1(D \setminus \rho(B))$ , where  $\rho$  runs over the set of rigid motions such that  $\rho(B) \subset D$ .

The first result obtained in this direction concerned the case where both D and B are disks of given radii. Indeed, it follows from Hersch's work [10] that the maximum of  $\lambda_1$  is achieved when the disks are concentric (see also [14]). This result has been extended to any dimension by several authors (Harrell, Kröger and Kurata [8], Kesavan [11], ...). Actually, Harrell, Kröger and Kurata [8] gave a more general result showing that, if the domain D satisfies an interior symmetry property with respect to a hyperplane P passing through the center of the spherical obstacle B

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(which means that the image by the reflection with respect to P of one component of  $D \setminus P$  is contained in D), then the Dirichlet fundamental eigenvalue  $\lambda_1(D \setminus B)$  decreases when the center of B moves perpendicularly to P in the direction of the boundary of D. In the particular case where both the domain D and the obstacle B are balls, this implies that the minimum of  $\lambda_1(D \setminus B)$  corresponds to the limit case where B touches the boundary of D.

Notice that when the obstacle B is a disk, only translations of B may affect the  $\lambda_1$  of  $D \setminus B$  and the optimal placement problem reduces to the choice of the center of B inside D.

In the present work we investigate a kind of dual problem in the sense that we consider a *nonspherical* obstacle B whose center of mass is fixed inside D, and seek the optimal positions while turning B around its center.

It is of course hopeless to expect a universal solution to this problem. In fact, we will restrict our investigation to a class of domains satisfying a dihedral symmetry and a monotonicity conditions.

Thus, let D be a simply-connected plane domain and assume that the following conditions are satisfied:

- (i)  $(\mathbb{D}_n$ -symmetry) for an integer  $n \geq 2$ , D is invariant under the action of the dihedral group  $\mathbb{D}_n$  of order 2n generated by the rotation  $\rho_{\frac{2\pi}{n}}$  of angle  $\frac{2\pi}{n}$  and a reflection S. Such a domain admits n axes of symmetry passing through the origin and such that the angle between 2 consecutive axes is  $\frac{\pi}{n}$ .
- (ii) (monotonicity of the boundary) the distance d(O, x) from the origin to a point x of the boundary of D is monotonous as a function of the argument of x, in a sector delimited by two consecutive symmetry axes.

Notice that assumption (i) guarantees that the center of mass of D is at the origin. Regular n-gones centered at the origin are the simplest examples of domains satisfying these assumptions. More generally, if g is any positive even  $\frac{2\pi}{n}$ -periodic continuous function that is monotonous on the interval  $(0, \frac{\pi}{n})$ , then the domain

$$D = \{ re^{i\theta}; \theta \in [0, 2\pi), 0 \le r < g(\theta) \},$$

satisfies assumptions (i) and (ii). Actually, up to a rigid motion, any domain satisfying assumptions (i) and (ii) can be parametrized in such a manner.

It is worth noticing that, due to the monotonicity condition, the "distance to the origin" function on the boundary of D achieves its maximum and its minimum alternatively at the intersection points of  $\partial D$  with the 2n half-axes of symmetry. The n points of  $\partial D$  at maximal (resp. minimal) distance from the origin will be called "outer vertices" (resp. "inner vertices") of D.

Our main result is the following

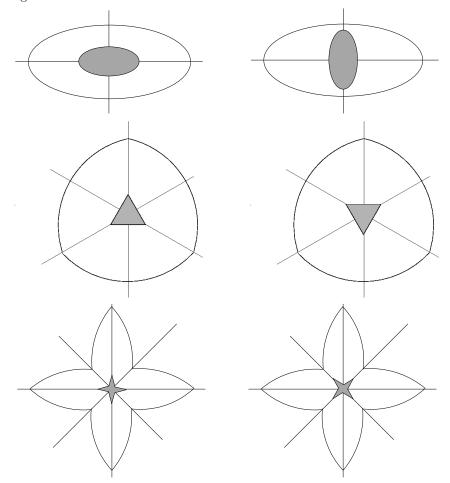
**Theorem 1.** Let D and B be two plane domains satisfying the assumptions of  $\mathbb{D}_n$ -symmetry and monotonicity (i) and (ii) above for an integer  $n \geq 2$ . Assume furthermore that B has  $C^2$  boundary and that  $\rho(B) \subset D$  for all  $\rho \in SO(2)$ . Then, the fundamental Dirichlet eigenvalue  $\lambda_1(D \setminus B)$  of  $D \setminus B$  is optimized exactly when the axes of symmetry of B coincide with those of D.

The maximizing configuration corresponds to the case where the outer vertices of B and D lie on the same half-axes of symmetry (we will then say that B occupies the "ON" position in D).

The minimizing configuration corresponds to the case where the outer vertices of B lie on the half-axes of symmetry passing through the inner vertices of D (this is what will be called the "OFF" position).

Actually, we will prove that, except for the trivial case where D or B is a disk, the fundamental Dirichlet eigenvalue of  $D \setminus B$  decreases gradually when B switches from "ON" to "OFF".

The main ingredients of the proof of Theorem 1 are Hadamard's variation formula for  $\lambda_1$  and the technique of domain reflection initiated by Serrin [17] in PDE's setting.



Examples of maximal (left) and minimal (right) configurations with n=2, 3 and 4 respectively

Extensions of Theorem 1 to the following situations can be obtained up to slight changes in the proof (indeed, only the Hadamard formula should be replaced by the variation formula corresponding to the new functional):

(1) Soft obstacles: instead considering the Dirichlet Laplacian on  $D \setminus B$ , we consider the Schrödinger type operator

$$H(\alpha, B) := \Delta - \alpha \chi_B$$

acting on  $H_0^1(D)$ , where  $\alpha > 0$  and  $\chi_B$  is the indicator function of B. Optimization problems related to the fundamental eigenvalue of operators of this kind have been investigated in particular in [8] and [3]. Under the assumptions of Theorem 1 on D and B,  $\forall \alpha > 0$ , the fundamental eigenvalue of  $H(\alpha, B)$  achieves its maximum at the "ON" position and its minimum at the "OFF" position.

- (2) Wells: this case corresponds to the operator  $H(\alpha, B)$  with  $\alpha < 0$ . Under the circumstances of Theorem 1,  $\forall \alpha < 0$ , the first eigenvalue of  $H(\alpha, B)$  achieves its maximum at the "OFF" position and its minimum at the "ON" position.
- (3) Stationary problem: the problem now is to optimize the Dirichlet energy  $J(D \setminus B) := \int_{D \setminus B} |\nabla u|^2 dx$  of the unique solution u of the problem

$$\left\{ \begin{array}{rcl} \Delta u & = & -1 & \text{in } D \setminus B \\ u & = & 0 & \text{on } \partial(D \setminus B), \end{array} \right.$$

This problem was treated in [11, Section 2] in the case where both D and B are balls. Under the assumptions of Theorem 1 on D and B, one can prove that  $J(D \setminus B)$  achieves its maximum when B is at the "ON" position and its minimum when B is at the "OFF" position.

## 2. Proof of the main result

Without loss of generality, we may assume that the domain D and the obstacle B are centered at the origin and are both symmetric with respect to the  $x_1$ -axis so that they can be parametrized in polar coordinates by

$$D = \{ re^{i\theta}; \theta \in [0, 2\pi), 0 \le r < g(\theta) \},\$$

$$B = \{re^{\mathbf{i}\theta}; \theta \in [0, 2\pi), 0 \le r < f(\theta)\},\$$

where f and g are two positive even  $\frac{2\pi}{n}$ -periodic functions which are nondecreasing on  $(0, \frac{\pi}{n})$ . To avoid technicalities, we suppose throughout that g is continuous and f is  $C^2$ . Extensions of our result to a wider class of domains would certainly be possible up to some additional technical difficulties.

The condition that the obstacle B can freely rotate around his center inside D, that is  $\rho(\bar{B}) \subset D$  for all  $\rho \in SO(2)$ , amounts to the following:

$$f(\frac{\pi}{n}) = \max_{0 \le \theta \le 2\pi} f(\theta) < \min_{0 \le \theta \le 2\pi} g(\theta) = g(0).$$

Let us denote, for all  $t \in \mathbb{R}$ , by  $\rho_t$  the rotation of angle t, that is,  $\forall \zeta \in \mathbb{R}^2 \cong \mathbb{C}$ ,  $\rho_t(\zeta) = e^{\mathbf{i}t}\zeta$ , and set

$$B_t := \rho_t(B)$$
 and  $\Omega(t) := D \setminus B_t$ .

Let  $\lambda(t)$  be the fundamental eigenvalue of the Dirichlet Laplacian on  $\Omega(t)$ . It is well known that, since it is simple, the first Dirichlet eigenvalue  $\lambda(t)$  is a differentiable function of t (see [6, 15]). We denote by u(t) the one parameter family of nonnegative first eigenfunctions satisfying,  $\forall t \in \mathbb{R}$ ,

$$\begin{cases} \Delta u(t) &= -\lambda(t)u(t) & \text{in } \Omega(t) \\ u(t) &= 0 & \text{on } \partial \Omega(t) \\ \int_{\Omega(t)} u^2(t) &= 1. \end{cases}$$

The derivative of  $\lambda(t)$  is then given by the following so-called Hadamard formula (see [4, 6, 7, 16]):

(1) 
$$\lambda'(t) = \int_{\partial B_t} \left| \frac{\partial u(t)}{\partial \eta_t} \right|^2 \eta_t \cdot v \ d\sigma,$$

where  $\eta_t$  is the inward unit normal vector field of  $\partial\Omega(t)$  (hence, along  $\partial B_t$  the vector  $\eta_t$  is outward with respect to  $B_t$ ) and v denotes the restriction to  $\partial \Omega(t) = \partial D \cup \partial B_t$ of the deformation vector field. In our case, the vector v vanishes on  $\partial D$  and is given by  $v(\zeta) = \mathbf{i}\zeta$  for all  $\zeta \in \partial B_t$ .

Since both  $\Omega$  and B are invariant by the dihedral group  $\mathbb{D}_n$ , it follows that,  $\forall t \in \mathbb{R}, \ \Omega(t+\frac{2\pi}{n})=\Omega_t$ . Moreover, if we denote by  $S_0$  the reflection with respect to the  $x_1$ -axis, then we clearly have  $\rho_{-t} = S_0 \circ \rho_t \circ S_0$  which gives  $B_{-t} = S_0(B_t)$ and  $\Omega_{-t} = S_0(\Omega_t)$ . Hence, as a function of t, the first Dirichlet eigenvalue of  $\Omega_t$  is even and periodic of period  $\frac{2\pi}{n}$ , that is,  $\forall t \in \mathbb{R}$ ,

$$\lambda(t + \frac{2\pi}{n}) = \lambda(t)$$
 and  $\lambda(-t) = \lambda(t)$ .

Therefore, it suffices to investigate the variations of  $\lambda(t)$  on the interval  $\left[0,\frac{\pi}{n}\right]$  and Theorem 1 is a consequence of the following:

**Theorem 2.** Assume that neither D nor B is a disk.

- (i)  $\forall t \in (0, \frac{\pi}{n}), \ \lambda'(t) < 0.$  Hence,  $\lambda(t)$  is strictly decreasing on  $(0, \frac{\pi}{n})$ .
- (ii)  $\forall k \in \mathbb{Z}, \ \lambda'(k\frac{\pi}{n}) = 0 \ and \ k\frac{\pi}{n}, \ k \in \mathbb{Z}, \ are the only critical points of \lambda on \mathbb{R}.$

Hence,  $\lambda(t)$  achieves its maximum for  $t=0 \mod \frac{2\pi}{n}$  which corresponds to the "ON" position, and its minimum for  $t=\frac{\pi}{n} \mod \frac{2\pi}{n}$  which corresponds to the "OFF" position. Of course, if D or B is a disk, then the function  $\lambda(t)$  is constant.

In what follows we will denote, for any  $\alpha \in \mathbb{R}$ , by  $z_{\alpha}$  the  $\theta = \alpha$  axis, that is  $z_{\alpha} := \{re^{\mathbf{i}\alpha}; \ r \in \mathbb{R}\}, \text{ and by } z_{\alpha}^{+} \text{ the half-axis } \{re^{\mathbf{i}\alpha}; \ r \geq 0\}.$ 

We start the proof with the following elementary lemma.

**Lemma 1.** Let K be a plane domain defined in polar coordinates by  $K = \{re^{i\theta}; \theta \in A\}$  $[0,2\pi), 0 \le r < h(\theta)$ , where h is a positive  $2\pi$ -periodic function of classe  $C^1$ , and let v be a vector field whose restriction to  $\partial K$  is given by

$$v(\theta) := v(h(\theta)e^{i\theta}) = ih(\theta)e^{i\theta} = h(\theta)e^{i(\theta + \frac{\pi}{2})}.$$

We denote by  $\eta$  the unit outward normal vector field of  $\partial K$ . One has, at any point  $h(\theta)e^{i\theta}$  of  $\partial K$  where  $\eta$  is defined,

- $$\begin{split} & \text{(i)} \ \, \eta(\theta) := \eta(h(\theta)e^{\mathbf{i}\theta}) = \frac{h(\theta)e^{\mathbf{i}\theta} \mathbf{i}h'(\theta)e^{\mathbf{i}\theta}}{\sqrt{h^2(\theta) + h'^2(\theta)}} \\ & \text{(ii)} \ \, \eta \cdot v(\theta) = \frac{-h(\theta)h'(\theta)}{\sqrt{h^2(\theta) + h'^2(\theta)}}. \ \, \textit{Hence,} \, \, \eta.v(\theta) \, \, \textit{has constant sign on an interval } I \end{split}$$
  if and only if h is monotonous in I.
- (iii) if for some  $\alpha > 0$ , the domain K is symmetric with respect to the axis  $z_{\alpha}$ , then the function  $\eta \cdot v$  is antisymmetric w.r.t this axis, that is

$$\eta \cdot v(\alpha + \theta) = -\eta \cdot v(\alpha - \theta).$$

*Proof.* Assertions (i) and (ii) are direct consequences from the definition of K. The fact that K is symmetric with respect to the axis  $z_{\alpha}$  implies that the function h satisfies  $h(\alpha + \theta) = h(\alpha - \theta)$ . Therefore, (iii) follows immediately from (ii).

We will denote by  $S_{\alpha}$  the symmetry with respect to the axis  $z_{\alpha}$ . We will also denote, for  $\alpha < \beta$ , by  $\sigma(\alpha, \beta)$  the sector delimited by  $z_{\alpha}^{+}$  and  $z_{\beta}^{+}$ , that is

$$\sigma(\alpha, \beta) = \{ re^{i\theta}; r > 0 \text{ and } \alpha < \theta < \beta \}.$$

**Lemma 2.** Let D be as above. For all  $t \in (0, \frac{\pi}{n})$ , we have:

$$S_{\frac{\pi}{n}+t}\left(D\cap\sigma\left(\frac{\pi}{n}+t,\frac{2\pi}{n}+t\right)\right)\subseteq D\cap\sigma\left(t,\frac{\pi}{n}+t\right).$$

Moreover, if D is not a disk, then

$$S_{\frac{\pi}{n}+t}\left(\partial D\cap\sigma\left(\frac{\pi}{n}+t,\frac{2\pi}{n}+t\right)\right)\cap D\neq\emptyset.$$

*Proof.* The action of the symmetry  $S_{\frac{\pi}{n}+t}$  is given in polar coordinates by  $S_{\frac{\pi}{n}+t}(re^{i\theta})=$  $re^{\mathbf{i}(2(\frac{\pi}{n}+t)-\theta)}$ . Hence,

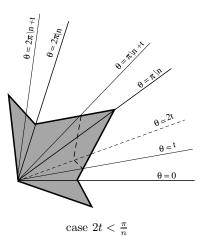
$$S_{\frac{\pi}{n}+t}\left(D\cap\sigma\left(\frac{\pi}{n}+t,\frac{2\pi}{n}+t\right)\right)=S_{\frac{\pi}{n}+t}(D)\cap\sigma\left(t,\frac{\pi}{n}+t\right).$$

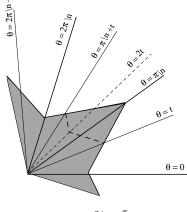
Moreover, the domain D being parametrized by a positive even  $\frac{2\pi}{n}$ -periodic function  $g(\theta)$ , that is  $D = \{re^{i\theta}; \theta \in [0, 2\pi), 0 \le r < g(\theta)\}$ , its image  $S_{\frac{\pi}{n}+t}(D)$  can be parametrized in the same manner by the function  $g^*(\theta) = g(\theta - 2t)$ . Thus

$$S_{\frac{\pi}{n}+t}(D) \cap \sigma\left(t, \frac{\pi}{n}+t\right) = \{re^{i\theta}; \theta \in \left(t, \frac{\pi}{n}+t\right), 0 \le r < g(\theta-2t)\}.$$

Therefore, we need to prove that  $F(\theta) = g(\theta) - g^*(\theta)$  is nonnegative for every  $\theta$  in the interval  $(t, \frac{\pi}{n} + t)$ . This will be possible thanks to the assumptions of symmetry (that is g is even and  $\frac{2\pi}{n}$ -periodic) and monotonicity (that is g is nondecreasing on  $[0,\frac{\pi}{n}]$ ). Indeed, these properties imply that on the interval  $(t,\frac{\pi}{n}+t)$ ,

- g achieves its maximum at  $\theta = \frac{\pi}{n}$ ,  $g^*$  achieves its minimum at  $\theta = 2t$ .





case  $2t > \frac{\pi}{n}$ 

Four cases must be considered separately:

- If  $t < \theta \le \min\{2t, \frac{\pi}{n}\}\$ , we may write, since g is even,  $F(\theta) = g(\theta) g(2t \theta)$ , with  $0 \le 2t - \theta < \theta \le \frac{\pi}{n}$ . Since g is nondecreasing on  $[0, \frac{\pi}{n}]$ , we get  $F(\theta) \ge 0$ .
- If  $\max\{2t,\frac{\pi}{n}\} \le \theta < \frac{\pi}{n} + t$ , we may write, since g is even and  $\frac{2\pi}{n}$ -periodic,  $F(\theta) = g(2\frac{\pi}{n} \theta) g(\theta 2t)$  with  $0 \le \theta 2t < 2\frac{\pi}{n} \theta \le \frac{\pi}{n}$ . Hence,  $F(\theta) \ge 0$ .

- If  $2t < \frac{\pi}{n}$  and  $2t \le \theta \le \frac{\pi}{n}$ , then  $0 \le \theta 2t < \theta \le \frac{\pi}{n}$  and, then,  $F(\theta) = g(\theta) g(\theta 2t) \ge 0$ .
- If  $2t > \frac{\pi}{n}$  and  $\frac{\pi}{n} \le \theta \le 2t$ , then  $0 \le 2t \theta < 2\frac{\pi}{n} \theta \le \frac{\pi}{n}$  and, then,  $F(\theta) = g(2\frac{\pi}{n} \theta) g(2t \theta) \ge 0$ .

Hence,  $F(\theta)$  is nonnegative for all  $\theta$  in  $(t, \frac{\pi}{n} + t)$ .

Now, if D is not a disk, then g is nonconstant on  $[0, \frac{\pi}{n}]$ . Following the arguments above, we deduce that the function  $F(\theta)$  is positive somewhere on  $(t, \frac{\pi}{n} + t)$  which means that  $S_{\frac{\pi}{n}+t}\left(\partial D \cap \sigma\left(\frac{\pi}{n} + t, \frac{2\pi}{n} + t\right)\right)$  meets the interior of D.

Proof of Theorem 2. Notice first that, since  $\lambda$  is an even and  $\frac{2\pi}{n}$ -periodic function of t, one immediately gets,  $\forall k \in \mathbb{Z}, \ \lambda(k\frac{\pi}{n}-t)=\lambda(k\frac{\pi}{n}+t)$  and, then,

$$\lambda'\left(k\frac{\pi}{n}\right) = 0.$$

Alternatively, one can deduce that  $\lambda'\left(k\frac{\pi}{n}\right) = 0$  from Hadamard's variation formula (1) after noticing that the domain  $\Omega(k\frac{\pi}{n})$  is symmetric with respect to the  $x_1$ -axis and that the first Dirichlet eigenfunction  $u(k\frac{\pi}{n})$  satisfies  $u \circ S_0 = u$ , where  $S_0$  is the symmetry with respect to the  $x_1$ -axis.

Let us fix a t in  $(0, \frac{\pi}{n})$  and denote by u the nonnegative first Dirichlet eigenfunction of  $\Omega(t)$  satisfying  $\int_{\Omega(t)} u^2 = 1$ . The domain  $\Omega(t)$  is clearly invariant by the rotation  $\rho_{\frac{2\pi}{n}}$  of angle  $\frac{2\pi}{n}$ , hence  $u \circ \rho_{\frac{2\pi}{n}} = u$ . On the other hand, the domain B being parametrized by a positive even  $\frac{2\pi}{n}$ -periodic function  $f(\theta)$ , that is  $B = \{re^{i\theta}; \theta \in [0, 2\pi), 0 \le r < f(\theta)\}$ , one has

$$B_t = \{ re^{i\theta}; \theta \in [0, 2\pi), 0 \le r < h(\theta) \},$$

with  $h(\theta) = f(\theta - t)$ . Hence, the function  $\eta_t \cdot v$  is invariant by  $\rho_{\frac{2\pi}{n}}$  (Lemma 1) and we have (Hadamard formula (1))

$$\lambda'(t) = \int_{\partial B_t} \left| \frac{\partial u}{\partial \eta_t} \right|^2 \eta_t \cdot v \ d\sigma = n \int_{\partial B_t \cap \sigma(t, \frac{2\pi}{t} + t)} \left| \frac{\partial u}{\partial \eta_t} \right|^2 \eta_t \cdot v \ d\sigma.$$

Since  $B_t$  is symmetric with respect to the axis  $z_{\frac{\pi}{n}+t}$ , we have (Lemma 1),  $\eta_t \cdot v(\frac{\pi}{n} + t + \theta) = -\eta_t \cdot v(\frac{\pi}{n} + t - \theta)$  or, equivalently,  $\eta_t \cdot v(x) = -\eta_t \cdot v(x^*)$ , where  $x^*$  denotes the symmetric of x with respect to  $z_{\frac{\pi}{n}+t}$ . This yields

$$\lambda'(t) = n \int_{\partial B_t \cap \sigma(\frac{\pi}{n} + t, \frac{2\pi}{n} + t)} \left( \left| \frac{\partial u}{\partial \eta_t}(x) \right|^2 - \left| \frac{\partial u}{\partial \eta_t}(x^*) \right|^2 \right) \eta_t \cdot v(x) \ d\sigma$$

Notice that the function  $h(\theta)$  is decreasing between  $\frac{\pi}{n} + t$  and  $\frac{2\pi}{n} + t$  and, then,  $\eta_t \cdot v$  is nonnegative on  $\partial B_t \cap \sigma(\frac{\pi}{n} + t, \frac{2\pi}{n} + t)$  (Lemma 1).

Let  $H(t) := \Omega(t) \cap \sigma(\frac{\pi}{n} + t, \frac{2\pi}{n} + t)$ . Applying Lemma 2, and since  $B_t$  is symmetric with respect to the axis  $z_{\frac{\pi}{n} + t}$ , one gets

$$S_{\frac{\pi}{n}+t}(H(t)) \subset \Omega(t) \cap \sigma(t, \frac{\pi}{n}+t).$$

Hence, the function  $w(x) = u(x) - u(x^*)$  is well defined on H(t) and satisfies w(x) = 0 for all x in  $\partial H(t) \cap \left(\partial B_t \cup z_{\frac{\pi}{n} + t} \cup z_{\frac{2\pi}{n} + t}\right)$ . Moreover, since u vanishes on  $\partial D$  and is positive inside  $\Omega(t)$ ,  $w(x) \leq 0$  for all x in  $\partial H(t) \cap \partial D$  and w(x) < 0 for certain x in  $\partial H(t) \cap \partial D$  (recall that D is not a disk and apply the second part of Lemma 2).

Therefore, the nonconstant function w satisfies the following:

$$\left\{ \begin{array}{rcl} \Delta w & = & -\lambda(t)w & \text{in } H(t) \\ w & \leq & 0 & \text{on } \partial H(t). \end{array} \right.$$

Hence, w must be nonpositive on the whole of H(t). Otherwise, a nodal domain  $V \subset H(t)$  of w would have the same first Dirichlet eigenvalue as  $\Omega(t)$ . But, due to the invariance of  $\Omega(t)$  by  $\rho_{\frac{2\pi}{n}}$ , the domain  $\Omega(t)$  would contain n copies of V leading to a strong contradiction with the domain monotonicity theorem for eigenvalues. Therefore,  $\Delta w \geq 0$  in H(t) and w achieves its maximal value (i.e. zero) on  $\partial B_t \cap \sigma(\frac{\pi}{n}+t,\frac{2\pi}{n}+t) \subset \partial H(t)$ . The Hopf maximum principle (see [13, Theorem 7, ch.2]) then implies that, at any regular point x of  $\partial B_t \cap \sigma(\frac{\pi}{n}+t,\frac{2\pi}{n}+t)$ , one has

$$\frac{\partial w}{\partial \eta_t}(x) = \frac{\partial u}{\partial \eta_t}(x) - \frac{\partial u}{\partial \eta_t}(x^*) < 0.$$

It follows that  $\lambda'(t) \leq 0$  and that the equality holds if and only if  $\eta_t \cdot v \equiv 0$ . By Lemma 1, this last equality occurs if and only if f is constant which means that B is a disk.

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